

eigenproblem of (block-) circulant matrices

Let $A = \begin{pmatrix} a_0 & a_{N-1} & \dots & a_1 \\ a_1 & a_0 & & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ a_{N-1} & a_{N-2} & \dots & a_0 \end{pmatrix}$ be a circular matrix.

What are the eigenvalues and eigenvectors of A ?

Let $Q = \begin{pmatrix} 0 & 0 & \dots & 1 \\ 1 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & 1 \end{pmatrix}$ Q denotes the shuffle by 1 step.
 Q^k - - - - - k steps.

Notice that $A = a_0 I + a_1 Q + \dots + a_{N-1} Q^{N-1}$.

Let $U(k, l) = \frac{1}{\sqrt{N}} e^{-2\pi j \frac{kl}{N}}$ (DFT matrix) $\cdot \sqrt{N}$

Fix k . Let $\xi = e^{-\frac{2\pi j}{N}}$, $p(x) = a_0 + a_1 x + \dots + a_{N-1} x^{N-1}$.

Then $Q^m \begin{pmatrix} e^{-2\pi j \frac{kl}{N}} \\ e^{-2\pi j \frac{k(l-1)}{N}} \\ \vdots \\ e^{-2\pi j \frac{k(N-1)l}{N}} \end{pmatrix} = Q^m \begin{pmatrix} e^{-2\pi j \frac{k \cdot 0}{N}} \\ e^{-2\pi j \frac{k \cdot 1}{N}} \\ \vdots \\ e^{-2\pi j \frac{k(N-1)}{N}} \end{pmatrix} = e^{-2\pi j \frac{k \text{ mod } N(m)}{N}} \begin{pmatrix} e^{-2\pi j \frac{kl}{N}} \\ \vdots \\ e^{-2\pi j \frac{k(N-1)l}{N}} \end{pmatrix}$
 $= \xi^{k \text{ mod } N(m)} \begin{pmatrix} e^{-2\pi j \frac{kl}{N}} \\ \vdots \\ e^{-2\pi j \frac{k(N-1)l}{N}} \end{pmatrix}$

So, $U Q^m U^{-1} = \text{diag} \left(1, \xi^{\text{mod } N(m)}, \xi^{2 \text{ mod } N(m)}, \dots, \xi^{(n-1) \text{ mod } N(m)} \right)$

$\Rightarrow U A U^{-1} = U P(Q) U^{-1}$

$= \text{diag} \left(p(1), p(\xi), \dots, p(\xi^{N-1}) \right) =: \tilde{A}$

$\Rightarrow A = U^{-1} \tilde{A} U$
diagonal

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So, the eigenvalues of A are $P(1), P(\xi), \dots, P(\xi^{N-1})$.

The corresponding eigenvectors are columns of $(\sqrt{N}U)^*$,

which are $\vec{w}_k = \begin{pmatrix} e^{\frac{j2\pi k}{N}} \\ \vdots \\ e^{\frac{j2\pi k}{N}(N-1)} \end{pmatrix}, k=0, \dots, N-1.$

A direct consequence is that all circulant matrices share same eigenvectors $\vec{w}_k, k=0, \dots, N-1.$

Next, we move on to block circulant matrices.

Let $H = \begin{pmatrix} H_0 & H_{N-1} & \dots & H_1 \\ H_1 & H_0 & \dots & H_2 \\ \vdots & \vdots & \ddots & \vdots \\ H_{N-1} & H_{N-2} & \dots & H_0 \end{pmatrix}$ be block circulant.
(each H_i is circulant),

Similarly, let $Q = \begin{pmatrix} 0 & & & 1 \\ 1 & 0 & & \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & 1 & 0 \end{pmatrix}$

Then, $H = I \otimes H_0 + Q \otimes H_1 + Q^2 \otimes H_2 + \dots + Q^{N-1} \otimes H_{N-1}$

One important property of Kronecker product:

Let A, B, C, D be matrices s.t. AC and BD are well-defined.

Then, $(A \otimes B)(C \otimes D) = (AC) \otimes (BD)$

(can be proved by direct computation) or properties of tensor product.

One observation (HW3 Q3)

$$\text{Let } W_N(n, k) = \frac{1}{\sqrt{N}} e^{2\pi j \frac{nk}{N}}$$

$$W_N \text{ is unitary. } W_N^{-1}(n, k) = W_N^*(n, k) = \overline{W_N}(n, k) = \frac{1}{\sqrt{N}} e^{-2\pi j \frac{nk}{N}}$$

$$\text{Let } W = W_N \otimes W_N. \text{ Then, } W^{-1} = \overline{W_N} \otimes \overline{W_N}.$$

$$\begin{aligned} \text{Then, } W(Q^m \otimes H_m)W^{-1} &= (W_N \otimes W_N) (Q^m \otimes H_m) (\overline{W_N} \otimes \overline{W_N}) \\ &= (W_N \otimes W_N) \left((Q^m \overline{W_N}) \otimes (H_m \overline{W_N}) \right) \\ &= (W_N Q^m W_N^{-1}) \otimes (W_N H_m W_N^{-1}) \end{aligned}$$

By previous arguments,

$$W_N Q^m W_N^{-1} = \text{diag} \left(1, \zeta^{\text{mod}_N(m)}, \zeta^{2 \text{mod}_N(m)}, \dots, \zeta^{(n-1) \text{mod}_N(m)} \right)$$

$$W_N H_m W_N^{-1} = \text{diag} \left(P_m(1), P_m(\zeta), \dots, P_m(\zeta^{N-1}) \right) =: \tilde{H}_m$$

$$\text{So, } W H W^{-1} = W \left(I \otimes H_0 + Q \otimes H_1 + \dots + Q^{N-1} \otimes H_{N-1} \right) W^{-1}$$

$$= \underbrace{\tilde{H}}_{\text{diagonal}}$$

Remark: In the lecture notes, you see the diagonalization of two matrices D and L . The formula follows from the above and Q3(b) in HW3.

How can we accelerate computation involving circular matrices using FFT?

Let A be a circular matrix.

$$A = \begin{pmatrix} a_0 & a_{N-1} & \dots & a_1 \\ a_1 & a_0 & & a_2 \\ \vdots & \vdots & \ddots & \vdots \\ a_{N-1} & a_{N-2} & \dots & a_0 \end{pmatrix}$$

Let x be a vector,

$$x = \begin{pmatrix} x_0 \\ x_1 \\ \vdots \\ x_{N-1} \end{pmatrix}$$

$$\text{Then, } A^T x = \begin{pmatrix} a_0 x_0 + a_1 x_1 + \dots + a_{N-1} x_{N-1} \\ a_{N-1} x_0 + a_0 x_1 + \dots + a_{N-2} x_{N-1} \\ a_{N-2} x_0 + a_{N-1} x_1 + \dots + a_{N-3} x_{N-1} \\ \vdots \\ a_1 x_0 + a_2 x_1 + \dots + a_0 x_{N-1} \end{pmatrix}$$

$\Rightarrow A^T x = a * x$, where a is a vector.

To compute $A^T x$, computation complexity is $O(N^2)$.

$$A^T x = a * x, \quad \text{DFT}(a * x) = \text{DFT}(a) \odot \text{DFT}(x)$$

$$a * x = \underbrace{\text{IDFT}}_{O(N \log N)} \left(\underbrace{\text{DFT}(a)}_{O(N \log N)} \odot \underbrace{\text{DFT}(x)}_{O(N \log N)} \right)$$

using FFT

\Rightarrow total cost: $O(N \log N)$